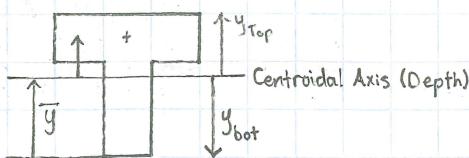


CIVI02 - STRUCTURES and MATERIALS

Topic: $\theta + \Delta$

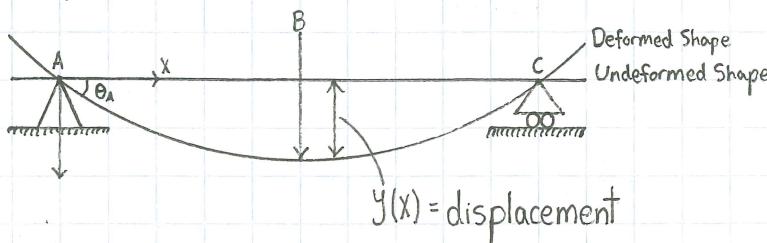
$$1) \sigma = \frac{My}{I}$$



$$|y_{bottom}| > |y_{top}|$$



2) Displacements of Beams



Small Displacements

$$\theta_A = \text{Angle} = \text{Shape} = \frac{dy}{dx} = \tan \theta$$

$$\phi \rightarrow M = EI\phi$$

$$\phi = \frac{M}{EI}$$

$$\phi = \frac{d\theta}{dx} = \frac{d}{dx} \left(\frac{du}{dx} \right) = \frac{d^2u}{dx^2}$$

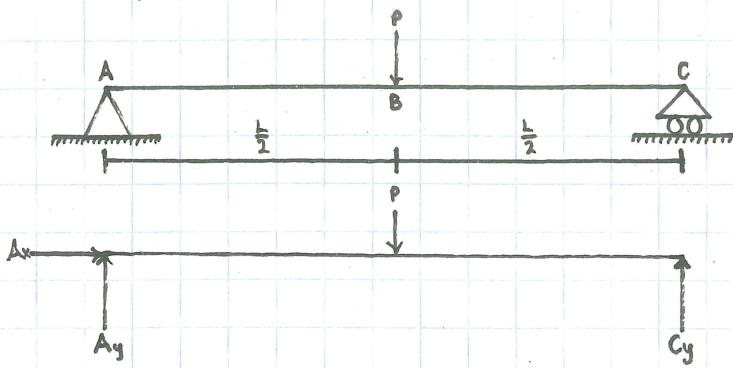
$$\boxed{\phi = \frac{d^2y}{dx^2}} \quad \text{if angles are small}$$

For larger angles

$$\phi = \frac{\frac{d^2u}{dx^2}}{\left(1 + \left(\frac{du}{dx}\right)^2\right)^{\frac{3}{2}}}$$

3) ϕ diagram

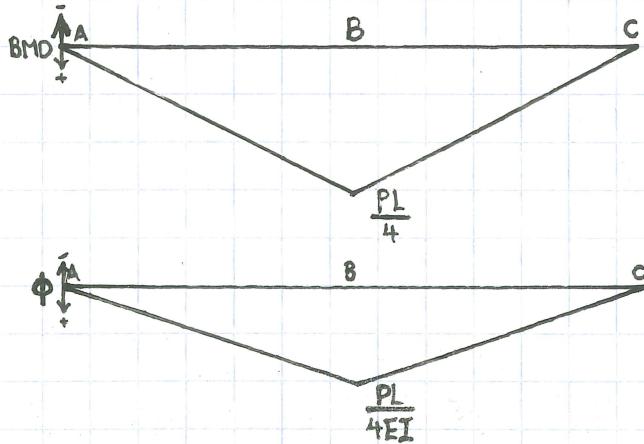
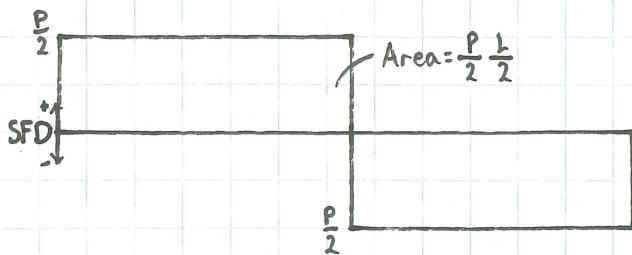
$$\phi = \frac{M}{EI}$$



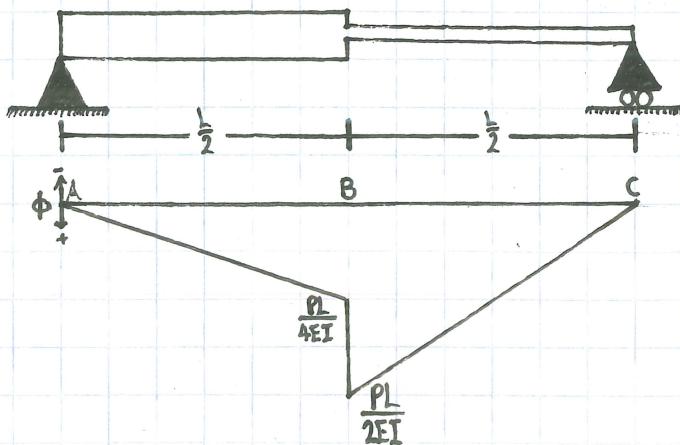
$$\sum F_x = 0, A_x = 0$$

$$\sum M_A = 0 = -P \cdot \frac{L}{2} + C_y \cdot L, C_y = \frac{P}{2}$$

$$\sum F_y = 0 = A_y + C_y - P, A_y = \frac{P}{2}$$



Problem 2



4) Solve for Displacements and Angles

↳ Calculus
↳ Moment Area Theorems

A) MAT #1 $\rightarrow \theta$

$\phi = \frac{d^2y}{dx^2}$, Integrate Once

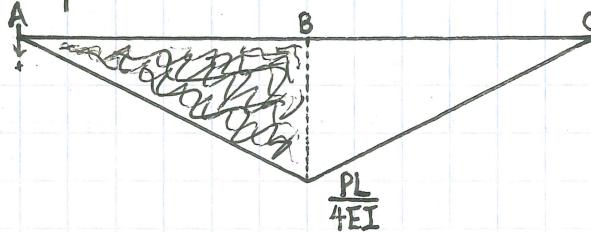
$$\int \phi dx + C = \frac{dy}{dx} = \theta$$

$$\theta = \int \phi dx + C$$

Moment Area Theorem #1

The change in slope between A and B in a beam is equal to the area under ϕ diagram between A and B.

Example



$$\theta_A = ?$$

by symmetry $\theta_B = \text{Zero}$

$$\theta_A - \theta_B = \text{Shaded Area} = \frac{1}{2} \cdot \frac{PL}{4EI} \cdot \frac{1}{2}$$

$$\boxed{\theta_A = \frac{PL^2}{16EI}}$$

B) MAT #2

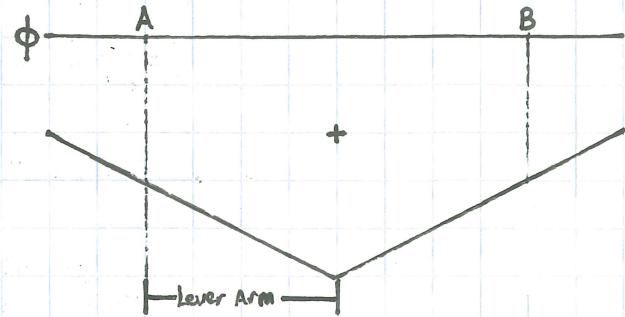
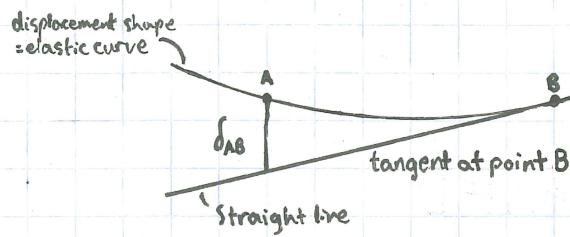
$$\int \phi dx + C_1 = \frac{dy}{dx}$$

$$\int \int \phi dx + C_1 x + C_2 = y$$

First Moment
of Area

Equation of
a Line

displacement perpendicular to undeformed shape
from the straight line



Moment Area Theorem #2

The tangential deviation δ_{AB} at point A between the elastic curve and the tangent drawn from B is equal to the first moment of area of the Φ diagram between A and B with moments taken about point A.

$$\delta_{AB}$$

A → Where to get δ

B → Where is the tangent

A → Where to get lever arm

$$\delta_{AB} = A_B \cdot (\text{lever arm})$$